

A Justification Logic with Common Knowledge

Samuel Bucheli

Institute of Computer Science and Applied Mathematics
University of Bern

Explicit Paradigms in Logic and Computer Science
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Justification Logic (Artemov 95)

modal logic

$\Box A$

A is known

A is provable

justification logic

$[t]A$

t is evidence for A

t is a proof for A

S4 and LP

S4 axioms & rules

$$\Box(A \rightarrow B) \rightarrow (\Box A \rightarrow \Box B)$$

$$\Box A \rightarrow A$$

$$\Box A \rightarrow \Box \Box A$$

modus ponens

$$\frac{A}{\Box A}$$

LP axioms & rules

$$[t](A \rightarrow B) \rightarrow ([s]A \rightarrow [t \cdot s]B)$$

$$[t]A \rightarrow A$$

$$[t]A \rightarrow [!t][t]A$$

$$[t]A \vee [s]A \rightarrow [t + s]A$$

modus ponens

$$\overline{[c]A}$$

where c is a constant
and A an axiom

Common Knowledge

Common Knowledge of A

everybody knows A and
everybody knows that everybody knows A and
everybody knows that everybody knows that everybody knows A
and
...

Another perspective

Common knowledge of A is the greatest fixed point of

$\lambda X.$ everybody knows A and everybody knows X .

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The system H_R (Fagin, Halpern, Moses, Vardi 95)

- ▶ All propositional tautologies
- ▶ $\Box_i(A \rightarrow B) \rightarrow (\Box_i A \rightarrow \Box_i B)$ (K)
- ▶ $\Box_i A \rightarrow A$ (T)
- ▶ $\Box_i A \rightarrow \Box_i \Box_i A$ (4)
- ▶ $CA \rightarrow E(A \wedge CA)$ (Co-CI)

and rules

$$\frac{A \quad A \rightarrow B}{B} \text{ (MP)} \quad \frac{A}{\Box_i A} \text{ (Nec)} \quad \frac{B \rightarrow E(A \wedge B)}{B \rightarrow CA} \text{ (I-R)}$$

The system H_{Ax} (Meyer, van der Hoek 95)

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$$\frac{A}{CA} \text{ (C-Nec)}$$

A Justification Logic for Common Knowledge: General Idea

- ▶ take a copy of a justification logic for each agent
- ▶ add evidence terms for mutual and common knowledge
- ▶ operation to tuple individual evidence

- ▶ operation to access tuple

- ▶ operation to generate “infinite list”

- ▶ operations to split list into head and tail

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$$\Box_1 A \wedge \dots \wedge \Box_h A \rightarrow EA$$

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$$CA \rightarrow EA, \quad CA \rightarrow ECA$$

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- ▶ operations to split list into head and tail

$$[t]_C A \rightarrow [\text{head}(t)]_E A, \quad [t]_C A \rightarrow [\text{tail}(t)]_E [t]_C A$$

Language

Let $\ast \in \{1, \dots, h, E, C\}$

Cons_{\ast} a countable set of proof constants for \ast

Var_{\ast} a countable set of proof variables for \ast

Prop a countable set of propositional variables.

Operations on Terms

- ▶ application and sum (for agents and C)
- ▶ positive inspection (for agents)
- ▶ tupling and projection (relates individual and mutual knowledge)
- ▶ induction and co-closure (relates mutual and common knowledge)

Formulae

$A ::= P_j \mid \perp \mid A \rightarrow A \mid [t]_{\ast} A$ where $t \in \text{Tm}_{\ast}$

LP_h^C : A Justification Logic with Common Knowledge

Axioms

1. all propositional tautologies
2. $[t]_*(A \rightarrow B) \rightarrow ([s]_*A \rightarrow [t \cdot s]_*B)$ (application)
3. $[t]_*A \vee [s]_*A \rightarrow [t + s]_*A$ (sum)
4. $[t]_iA \rightarrow A$ (reflexivity)
5. $[t]_iA \rightarrow [!t]_i[t]_iA$ (inspection)
6. $[t_1]_1A \wedge \dots \wedge [t_h]_hA \rightarrow [\langle t_1, \dots, t_h \rangle]_EA$ (tupling)
7. $[t]_EA \rightarrow [\pi_i t]_iA$ (projection)
8. $[t]_CA \rightarrow [\text{head}(t)]_EA, \quad [t]_CA \rightarrow [\text{tail}(t)]_E[t]_CA$ (co-closure)
9. $[t]_C(A \rightarrow [r]_EA) \rightarrow ([s]_EA \rightarrow [\text{ind}(t, s)]_CA)$ (induction)

where $* \in \{1, \dots, h, C\}$.

Rules *modus ponens* and *axiom necessitation*

$$\frac{A \quad A \rightarrow B}{B} \quad (\text{MP}) , \quad \frac{}{[c]_cD} \quad (\text{AN}) ,$$

where $c \in \text{Cons}_C$ and D is an axiom from the list above.

Constructive Necessitation and Induction Rule

Theorem

If $\vdash A$, then, for each \ast there exists a ground term t_{\ast} such that

$$\vdash [t]_{\ast}A .$$

Corollary

If $\vdash B \rightarrow [s]_E(A \wedge B)$, then there exists a ground term t such that

$$\vdash B \rightarrow [t]_C A .$$

Definable Operations

Lemma

The following operations can be defined

- ▶ $[t]_E(A \rightarrow B) \rightarrow ([s]_E \rightarrow [t \cdot_E s]_E B),$
- ▶ $[t]_E A \vee [s]_E A \rightarrow [t +_E s]_E A,$
- ▶ $[t]_C A \rightarrow [\downarrow i]_i A,$
- ▶ $[t]_C A \rightarrow [\uparrow i]_i [t]_C A,$
- ▶ $[t]_C A \rightarrow [!ct]_C [t]_C A,$
- ▶ $[t]_C A \rightarrow [\Leftarrow t]_C [\text{head}(t)]_E A.$

Epistemic Models

An epistemic model is a quadruple $\mathcal{M} = (W, R, \mathcal{E}, \nu)$, where (W, R, ν) is a Kripke model, i.e.,

- ▶ W is a non-empty set called **possible worlds**.
- ▶ $R: \{1, \dots, h\} \rightarrow \mathcal{P}(W \times W)$ assigns a transitive and reflexive **accessibility relation** to each agent.
- ▶ $\nu: \text{Prop} \rightarrow \mathcal{P}(W)$ is a **truth valuation**.

and

- ▶ $\mathcal{E}: W \times \text{Tm} \rightarrow \mathcal{P}(\text{Fm}_{\text{LP}_h^C})$ is an **evidence function** determining the formulae evidenced by a term at a world.

Furthermore

- ▶ $R_E := \bigcup_{i=1}^h R_i$,
- ▶ $R_C := \bigcup_{n=1}^{\infty} (R_E)^n$, i.e. R_C is the **transitive closure** of R_E .

Satisfaction Relation

- ▶ $\mathcal{M}, w \Vdash P$ if and only if $w \in \nu(P)$;
- ▶ \Vdash behaves classically with respect to propositional connectives;
- ▶ $\mathcal{M}, w \Vdash [t]_{\otimes} A$ if and only if
 - 1) $A \in \mathcal{E}_{\otimes}(w, t)$ and
 - 2) $\mathcal{M}, v \Vdash A$ for all $v \in W$ with $(w, v) \in R_{\otimes}$.

$[t]A$ if and only if

A is true in all possible worlds and t is admissible evidence for A .

Coordinated Attack

General G

General H

Coordinated Attack

General G

General H

$\Rightarrow m_1$: "attack at dawn" \Rightarrow

Coordinated Attack

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$\Rightarrow m_1$: "attack at dawn" \Rightarrow

$[m_1]_{Hdel}$

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$\Rightarrow m_1: \text{"attack at dawn"} \Rightarrow$

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$\neg [s]_G [m_1]_{Hdel}$

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$\Rightarrow m_1: \text{"attack at dawn"} \Rightarrow$

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$\Leftarrow m_2: \text{"acknowledged"} \Leftarrow$

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\vdots

Soundness, Completeness and Decidability

Theorem

LP_h^C is sound and complete with respect to its class of epistemic models.

Corollary

LP_h^C is complete with respect to the class of singleton models.

Theorem

LP_h^C is decidable.

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Conservativity

Theorem

LP_h^C is a conservative extensions of its corresponding multi-agent justification logic (without common knowledge).

Corollary

LP_2^C is a conservative extension of Yavorskaya's minimal bimodal explicit evidence logic LP_2 .

Realization

Lemma

If $LP_h^C \vdash A$, then $S4 \vdash A^\circ$.

Question

What about the other direction?

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Fitting's Semantical Realization Technique

Observation

Fitting's technique relies only on a certain form of the canonical model, the Truth Lemma, and Constructive Necessitation.

Idea

If all possible realizations of a formula fail in a world of the canonical model, then also the forgetful projection of this formula must fail in the same world.

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Conclusions

- ▶ common knowledge is a natural addition to multi-agent justification logics
- ▶ alternative possibilities in analyzing epistemic scenarios
- ▶ major open problem: realization
- ▶ another interesting question: complexity
- ▶ long-term goal: dynamic epistemic logics
- ▶ more model theoretic tools
- ▶ justification logics without corresponding (normal) modal logics?